

# Integration of the MATSim transport model into the DAFNI platform

J. Raimbault<sup>1,2,3,\*</sup>

\*j.raimbault@ucl.ac.uk

<sup>1</sup>Center for Advanced Spatial Analysis, University College London <sup>2</sup>UPS CNRS 3611 Complex Systems Institute Paris <sup>3</sup>UMR CNRS 8504 Géographie-cités

> DAFNI Roadshow - UTSG 24th March 2021

## MATSim model: heterogenous data and integration of many sub-models



#### Source: [Balmer et al., 2009]

Raimbault (UCL)



## Land-use transport models as a progressive complexification through coupling of detailed sub-models

Transport model		T1 No public transport no modal split	T2 Public transport no logit 24 h	T3 Public transport logit peak hour	T4 Multi- modal activity -based	
LI	None	/		→	→ I	
L2	Activity and judgement			*		
L3	No market-based land allocation	$\square$		\$	+	
L4	Logit allocation with price signals		$\square$		+	
L5	Market-based land-use model					
L6	Activity-based land-use model				**	

	Speed of change									
Models	Very slow		Slow		Fast		Immediate			
	Networks	Land use	Work- places	Housing	Employ- ment	Popula- tion	Goods transport	Travel		
BOYCE	+				+	+		+		
CUFM		+	+	+	+	+				
DELTA/START	+	+	+	+	+	+	+	+		
HUDS				+	+	+				
IMREL	+	+	+	+	+	+		+		
IRPUD	+	+	+	+	+	+		+		
ITLUP	+	+			+	+		+		
KIM	+				+	+	+	+		
LILT	+	+	+	+	+	+		+		
MEPLAN	+	+	+	+	+	+	+	+		
METROSIM	+	+	+	+	+	+		+		
MUSSA	+	+			+	+		+		
POLIS		+			+	+		+		
RURBAN		+			+	+		+		
STASA	+	+	+	+	+	+	+	+		
TRANUS	+	+	+	+	+	+	+	+		
URBANSIM		+	+	+	+	+		+		

#### Source: [Wegener and Fürst, 2004]

Build modular urban transportation models from the bottom-up using scientific workflow systems, open source sub-models and open data

- ightarrow Sub-models coupled into the workflow, can be easily replaced
- ightarrow Reproducibility and transparency
- $\rightarrow$  Easier transferability of model application
- ightarrow Application of model validation methods

**Implementation:** *integration of the MATSim transport model into the DAFNI platform* 



**Case study:** Construct a modular four-step multimodal transportation model using open source projects and data

#### Integrated models:

- MATSim model (MATSim Community) for the transportation system https://www.matsim.org/ [Horni et al., 2016]
- SPENSER model (University of Leeds) for the synthetic population https://github.com/nismod/microsimulation
- QUANT model (CASA, University College London) for spatial interactions to generate home-work plans http://quant.casa.ucl.ac.uk/ [Milton and Roumpani, 2019] (specific scala implementation)
- spatialdata library (OpenMOLE community) for data processing https://github.com/openmole/spatialdata [Raimbault et al., 2020]



#### Data:

Generic for any Functional Urban Area (GHSL [Florczyk et al., 2019]) in the UK: NOMIS census, OrdnanceSurvey roads, Transport National Dataset

#### Implementation

Currently integrated into the DAFNI platform:

- synthetic SPENSER population with uniform job locations
- QUANT model to generate home-work commuting flows
- network and plans prepared into MATSim xml files and fed into a one-mode MATSim (multimodal version still tested locally)
- models integrated as Docker containers

## DAFNI workflow for coupled model



## Visualization within DAFNI



## Simulation results: travel distances

**UCL** 



Raimbault (UCL)

MATSim transport modelling

## Daily travel patterns

**UC** 



## Role of stochasticity



FUA: Taunton



## Validation: towards spatial sensitivity analysis



Raimbault, J., Cottineau, C., Le Texier, M., Le Nechet, F., Reuillon, R. (2019). Space Matters: Extending Sensitivity Analysis to Initial Spatial Conditions in Geosimulation Models. *Journal of Artificial Societies and Social Simulation*, 22(4).

Raimbault, J., Perret, J., & Reuillon, R. (2020). A scala library for spatial sensitivity analysis. GISRUK 2020 Proceedings, 32.







Raimbault, J., Perret, J. (2019). Generating urban morphologies at large scales. In *Artificial Life Conference Proceedings* (pp. 179-186).

#### Raimbault (UCL)

OpenMOLE model exploration open source software [Reuillon et al., 2013]



Enables seamlessly (i) model embedding; (ii) access to HPC resources; (iii) exploration and optimization algorithms

https://openmole.org/

## Towards advanced validation experiments



**OpenMOLE integrates methods for:** sensitivity analysis, spatial sensitivity analysis, design of experiments, calibration, diversity search, inverse problems, model reduction.



#### Integration of OpenMOLE into DAFNI

Raimbault (UCL)

## **UCL**

## Developments

 $\rightarrow$  Integration of multi-modal MATSim, calibration of mode choice parameters

 $\rightarrow$  Visualisation of MATSim agents dynamics (MATSim visu features not open)

 $\rightarrow$  Dynamical strong coupling of QUANT and SPENSER to combine population projections with the transport model

## Applications

 $\rightarrow$  Validation of sub-models and integrated models using advanced model validation methods

 $\rightarrow$  Use MATSim outputs to quantify effective densities in public transport: potential exposure indicators in the COVID-19 context

 $\rightarrow$  Impact of policies and interventions on transport system dynamics and potential contaminations

**UCL** 

 $\rightarrow$  Open, reproducible and validated urban models as elementary bricks towards larger integrated models

 $\rightarrow$  Central role of the DAFNI platform: workflow system to couple models, data platform, integrated access to computational resources

#### **Open repositories**

https://github.com/JusteRaimbault/UrbanDynamics for workflows https://github.com/openmole/spatialdata for data processing

#### Workflow engines

```
DAFNI: https://dafni.ac.uk/
```

OpenMOLE: https://openmole.org

## **References** I

UCL

Balmer, M., Rieser, M., Meister, K., Charypar, D., Lefebvre, N., and Nagel, K. (2009).
Matsim-t: Architecture and simulation times.
In *Multi-agent systems for traffic and transportation engineering*, pages 57–78. IGI Global.

- Florczyk, A. J., Corbane, C., Ehrlich, D., Freire, S., Kemper, T., Maffenini, L., Melchiorri, M., Pesaresi, M., Politis, P., Schiavina, M., et al. (2019).
   Ghsl data package 2019.
   Luxembourg, EUR, 29788(10.2760):290498.
- Horni, A., Nagel, K., and Axhausen, K. W. (2016). *The multi-agent transport simulation MATSim.* Ubiquity Press.



Milton, R. and Roumpani, F. (2019). Accelerating urban modelling algorithms with artificial intelligence. In *Proceedings of the 5th International Conference on Geographical Information Systems Theory, Applications and Management*, volume 1, pages 105–116. INSTICC.

Raimbault, J., Perret, J., and Reuillon, R. (2020). A scala library for spatial sensitivity analysis. *Proceedings of GISRUK 2020*.

Reuillon, R., Leclaire, M., and Rey-Coyrehourcq, S. (2013). Openmole, a workflow engine specifically tailored for the distributed exploration of simulation models.

*Future Generation Computer Systems*, 29(8):1981–1990.





Wegener, M. and Fürst, F. (2004). Land-use transport interaction: State of the art. *Available at SSRN 1434678.*